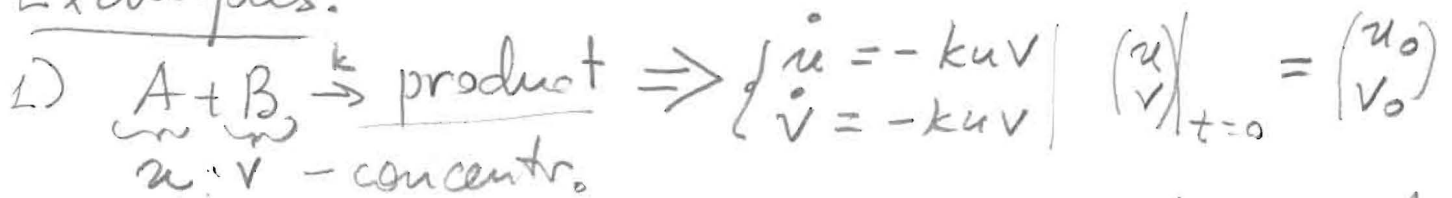


# Reaction - diffusion in 1D

D. GARARIE

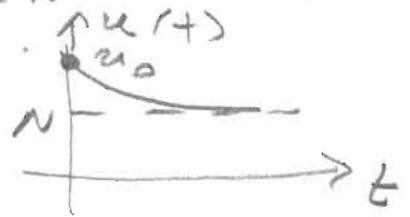
$$\begin{cases} u_t = \underbrace{D u_{xx}}_{\text{diff.}} + \underbrace{f(u)}_{\text{react}}; & \text{BC} \dots \end{cases}$$

Examples:



Mass conserv.  $\Rightarrow u - v = u_0 - v_0 = N$  - const

$\Rightarrow$  Logistic DE:  $\boxed{\dot{u} = kN \left(1 - \frac{u}{N}\right) u}$



2) FK model (slow evolution of allele freq.)

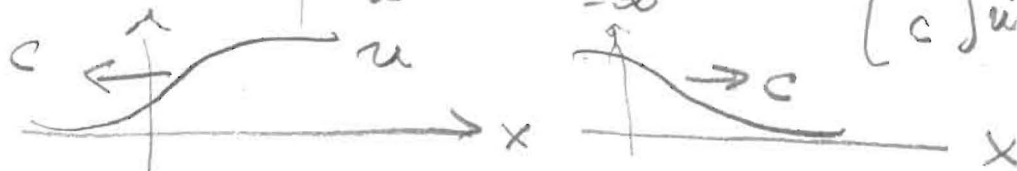
$$\boxed{p_t = D p_{xx} + a p(1-p)}$$

I. Equilibria:  $\begin{cases} u'' + f(u) = 0 \\ \text{BC} \dots \end{cases}$   
 $u(x)$

II. Traveling waves:  $\begin{cases} u'' + cu' + f(u) = 0 \\ u|_{-\infty} = \dots \quad u|_{\infty} = \dots \end{cases}$   
 $u(x-ct)$

Monotone profiles

$$0 = \frac{c^2}{2} \int_{-\infty}^{\infty} u'^2 dx + c \int_{-\infty}^{\infty} u'^2 dx + \int_{-\infty}^{\infty} f(u) u' dx = \begin{cases} c \int_{-\infty}^{\infty} u'^2 dx + \int_0^1 f(u) du \Rightarrow c < 0 \text{ left} \\ c \int_{-\infty}^{\infty} u'^2 dx - \int_0^1 f(u) du \Rightarrow c > 0 \text{ right} \end{cases}$$



# Classical mech. systems in 1D

$x$  - position  
 $\dot{x} = v$  - velocity

$$m \ddot{x} = -f(x, \dot{x}, \dots)$$

Potential force

$$f(x) = -U'(x)$$

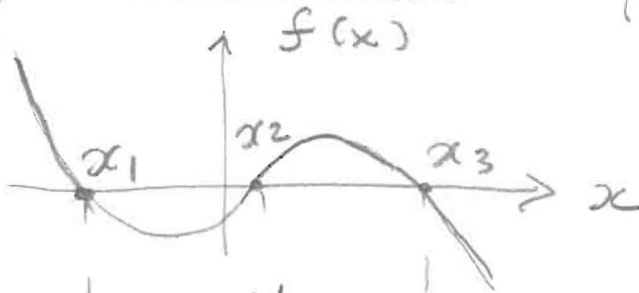
(1) 
$$\begin{cases} \dot{x} = v \\ \dot{v} = f(x) - c v \end{cases}$$

$\uparrow$   $\uparrow$   
 potent. friction

## Energy conservation

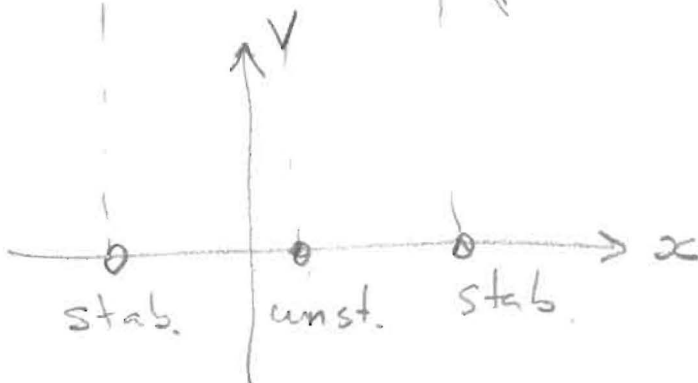
$$E = \frac{mv^2}{2} + U(x) - \text{const. for any trajectory } \begin{cases} x(t) \\ v(t) \end{cases}$$

Equilibria (1):  $\{(x_k, 0) : f(x_k) = 0\}$



Stability / Jac.


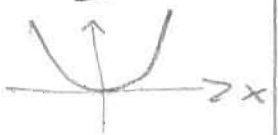
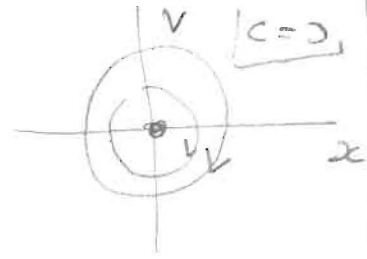
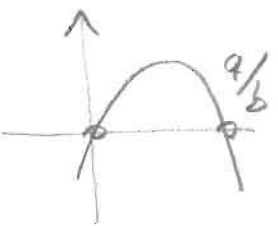
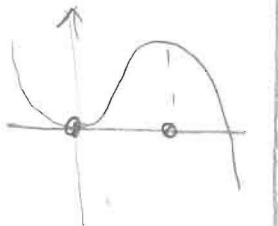
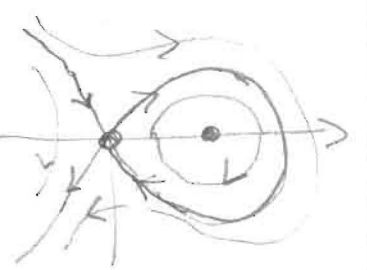
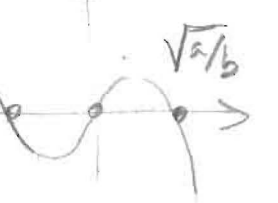

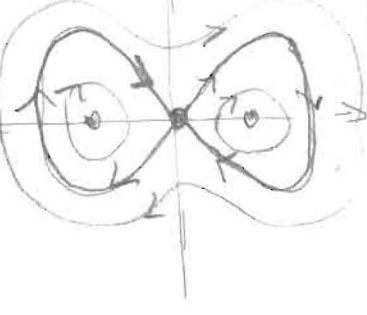
$$J_k = \begin{bmatrix} 0 & 1 \\ f'(x_k) & -c \end{bmatrix}$$



$x_1$	$x_2$	$x_3$
$\begin{bmatrix} 0 & 1 \\ + & -c \end{bmatrix}$	$\begin{bmatrix} 0 & 1 \\ + & -c \end{bmatrix}$	$\begin{bmatrix} 0 & 1 \\ - & -c \end{bmatrix}$

# Examples:

(2)

$f(x)$	$U(x)$	Ph. plane equil!	Jac.
① $-kx$ 	$\frac{kx^2}{2}$ 		$(0,0)$ $\begin{bmatrix} 0 & 1 \\ -k & -c \end{bmatrix}$ cent. $\rightarrow$ sp. sink $\rightarrow$ sink
② $ax - bx^2$ 	$\frac{ax^2}{2} - \frac{bx^3}{3}$ 		$(0,0)$   $(x_1, 0)$ $\begin{bmatrix} 0 & 1 \\ a & -c \end{bmatrix}$   $\begin{bmatrix} 0 & 1 \\ -a & -c \end{bmatrix}$ saddle   cent. sp. sink sink
③ $ax - bx^3$ 	$\frac{ax^2}{2} - \frac{bx^4}{4}$ 		$(0,0)$   $(\pm x_1, 0)$ $\begin{bmatrix} 0 & 1 \\ a & -c \end{bmatrix}$   $\begin{bmatrix} 0 & 1 \\ -a & -c \end{bmatrix}$ saddle   cent. sp. sink sink

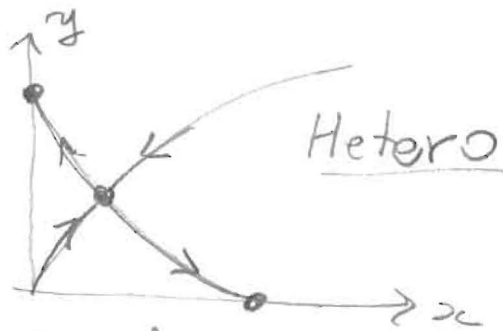
Friction ( $c > 0$ ):

saddle  $\rightarrow$  saddle  
 center  $\rightarrow$  sp. sink  
 $\rightarrow$  sink

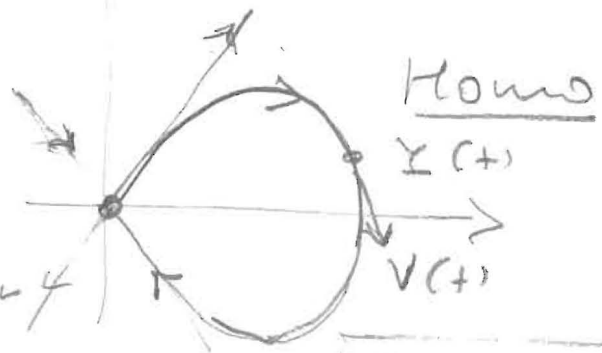
# Stable / unstable orbits (3)

(homo- & hetero-clinic)

Each saddle has stable + unstable orbits (2)-(3)



Exclusive competition



DE: 1) standard orbit: IVP  $\begin{cases} \dot{y} = F(y) \\ y(0) = y_0 \end{cases}$  v.f.

2) Stable / unst: (n)  $\ddot{y} = \underbrace{F'(y)}_{\text{Jacob.}} \cdot \dot{y}(t) \iff$

$$(2n) \begin{cases} \dot{y} = V \\ \dot{V} = F'(y) \cdot V \end{cases}$$

BC:  $V(-\infty) = V_-$  - unst. eigen  
 $V(+\infty) = V_+$  - stab. eigen

# Analysis of traveling wave of Fisher-Kolmogorov.

D. GURARIE

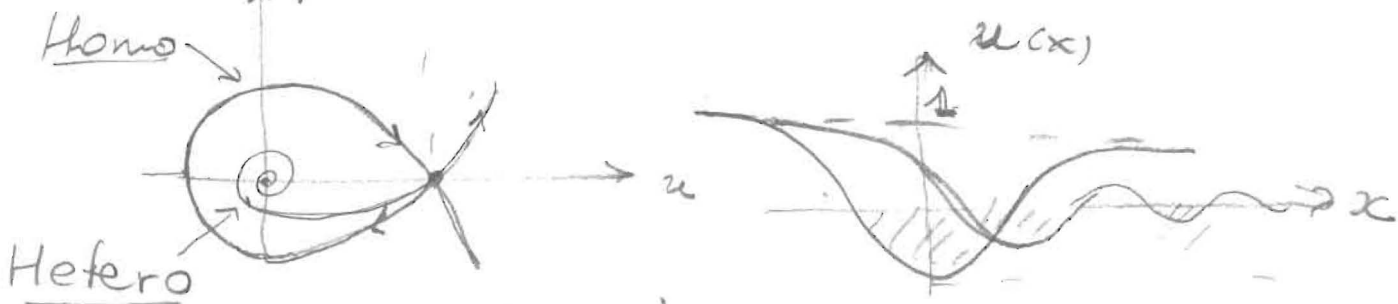
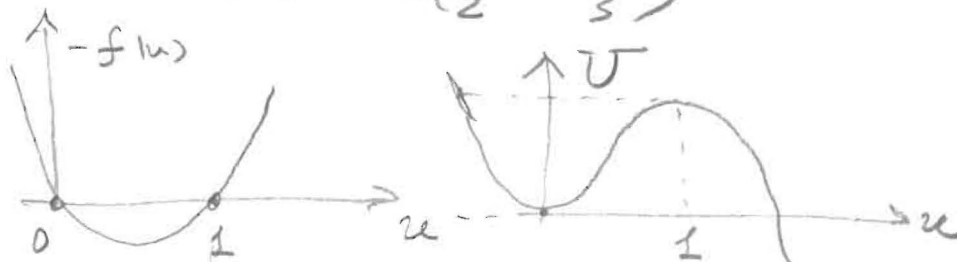
$$(FK) \begin{cases} Du_{xx} + cu_x + f(u) = 0; & f = au(1-u) \\ u|_{-\infty} = 1; & u|_{+\infty} = 0; \end{cases}$$

Rescale:  $(a, c) \rightarrow (\frac{a}{D}, \frac{c}{D})$

Write DS:  $\begin{cases} u' = v \\ v' = -f(u) - cv \end{cases}$

"Potential & cons. integral ( $c=0$ )

$$U(u) = a\left(\frac{u^2}{2} - \frac{u^3}{3}\right)$$



For traveling wave ( $u(x) \geq 0$ ) need  
bifurcation at  $(0,0)$ : sp. sink  $\rightarrow$  sink

$$\begin{array}{c|c} (1, 0)' & (0, 0) \\ \hline \begin{bmatrix} 0 & 1 \\ -a & -c \end{bmatrix} & \begin{bmatrix} 0 & 1 \\ a & -c \end{bmatrix} \end{array}$$

(2)

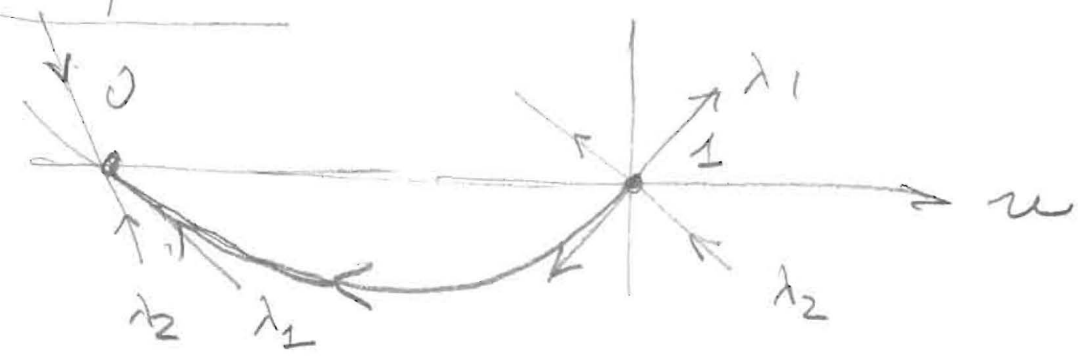
$$a = f'(0) = -f'(1)$$

$$\lambda_{1,2} = -\frac{c}{2} \pm \sqrt{\frac{c^2}{4} - a} \quad \lambda_{1,2} = -\frac{c}{2} \pm \sqrt{\frac{c^2}{4} + a}$$

$$0 > \lambda_1 > \lambda_2$$

$$\begin{array}{c|c} \lambda_1 & \lambda_2 \\ \hline \begin{pmatrix} 1 \\ \lambda_1 \end{pmatrix} & \begin{pmatrix} 1 \\ \lambda_2 \end{pmatrix} \end{array}$$

$$\begin{array}{c|c} \lambda_1 & \lambda_2 \\ \hline \begin{pmatrix} 1 \\ \lambda_1 \end{pmatrix} & \begin{pmatrix} 1 \\ \lambda_2 \end{pmatrix} \end{array}$$



For all  $a \leq \frac{c^2}{4} \iff c \geq 2\sqrt{a}$

trav. wave

$$\frac{c}{D} \geq 2\sqrt{\frac{a}{D}} \implies c \geq 2\sqrt{aD}$$

$$D u_{xx} + a u(1-u) + c u_x$$

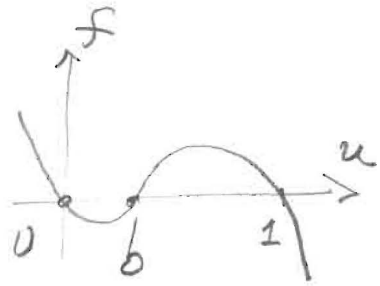
Need sufficiently high  $c \geq c_m = 2\sqrt{aD}$

condition for traveling wave

## Modified FK

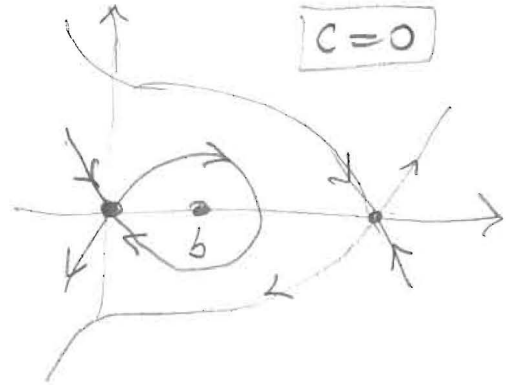
(3)

$$u_t = Du_{xx} + \underbrace{a u (u-b)(1-u)}_f$$



Condition for monotone wave:

$$c \int_{-\infty}^{\infty} u'^2 dx \pm \int_0^1 f(u) du = 0$$



Problem: i) find bifurcation values on  $(b,c)$ -parameter space for traveling wave  $u|_{-\infty} = 1; u|_{\infty} = 0$

ii) Demonstrate numerically in phase-plane & solution plots.

Unlike standard FK  $f(u) = u(1-u)$  modified  $f = u(1-u)(u-b)$  has only one critical speed for each  $b$ !

Rescaled SIR w. diffusion:

spread of rabies by foxes

- (\*) Healthy foxes stay home
- (\*) Infected - wander around (diffuse)
- (\*) R-group dies (lethal)

$$(1) \left\{ \begin{array}{l} S_t = -\beta SI \\ I_t = \beta SI - \gamma I + D I_{xx} \\ R_t = \gamma I \end{array} \right. \Rightarrow N = \int (S+I+R) dx = \text{const} \quad \text{Total}$$

1° Rescale:  $\begin{pmatrix} S \\ I \\ R \end{pmatrix} \rightarrow \begin{pmatrix} u \\ v \\ w \end{pmatrix} = \frac{1}{N} \begin{pmatrix} S \\ I \\ R \end{pmatrix}; \quad t \rightarrow \gamma t$   
 $x \rightarrow \sqrt{\frac{D}{\gamma}} x$   
 $R_0 = \frac{\beta N}{\gamma}$

D-less:  
R-D (2)  $\left\{ \begin{array}{l} u_t = -uv \\ v_t = uv - v + v_{xx} \\ w_t = v \end{array} \right.$

2° Traveling wave:  $\left\{ \begin{array}{l} u(x+ct) \\ - \\ - \\ - \end{array} \right. = \underline{\underline{3}} = \text{charact. coord.}$

$\Rightarrow (3) \left\{ \begin{array}{l} cu' = -R_0 uv \\ v'' - cv' = -(R_0 u - 1) \\ w' = v \end{array} \right. \quad \underline{\underline{3}}^{\text{rd}} \text{ order}$

Derivatives:  $u' = \frac{du}{d\zeta}; \quad v' = \dots$

3<sup>o</sup> Conserved integral: (2)

$$(4) \left\{ \begin{array}{l} \left(\frac{1}{c} v' - v\right)' = -\frac{(R_0 u - 1)}{c} v \\ u' = -\frac{R_0 u v}{c} \\ w' = v \end{array} \right\} \Rightarrow (5) \left\{ \begin{array}{l} \frac{d\left(\frac{v'}{c} - v\right)}{du} = 1 - \frac{1}{R_0 u} \\ \frac{dw}{du} = -\frac{1}{R_0 u} \end{array} \right.$$

eliminate indep. variable  $\xi$

4<sup>o</sup> Integration of (5)

$$(6) \left\{ \begin{array}{l} \frac{v'}{c} - v = \left(u - \frac{1}{R_0} \ln u\right) - A \\ w = -\frac{1}{R_0} \ln u + B \end{array} \right. \leftarrow \begin{array}{l} \text{constants} \\ \text{of integral} \end{array}$$

BC:

	$+\infty$	$-\infty$
$u$	1	$u_1$
$v$	0	0
$v'$	0	0
$w$	0	$w_1$

$$\Rightarrow \left\{ \begin{array}{l} A = 1 \\ B = 0 \end{array} \right\} \oplus$$

$\oplus$  algebraic eq-n for  $u_1 + w_1 = 1$

$$1 - w_1 = e^{-R_0 w_1} \Rightarrow R_0 > 1$$

5<sup>o</sup> Reduced 2D system:

$$(7) \left\{ \begin{array}{l} u' = -\frac{R_0}{c} u v \\ v' = c \left(u - \frac{1}{R_0} \ln u - 1 + v\right) \end{array} \right. \text{ change: } u \rightarrow q = -\frac{c}{R_0} \ln u$$

Phase-plane analysis

$$(8) \left\{ \begin{array}{l} q' = v \\ v' = c \left( e^{-R_0 q/c} - 1 - q \right) + c v \end{array} \right.$$

